

IF  SENSOR
R25



OPTICAL 3D SENSOR FOR HIGH RESOLUTION QUALITY ASSURANCE IN RESEARCH AND PRODUCTION

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Agenda

- » Characteristics
- » Applications
- » Unique features
- » System integration

CHARACTERISTICS

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Optical 3D surface measurement device

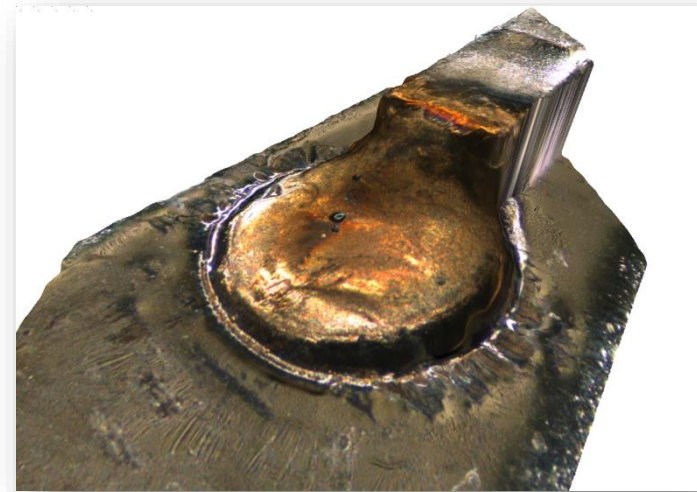
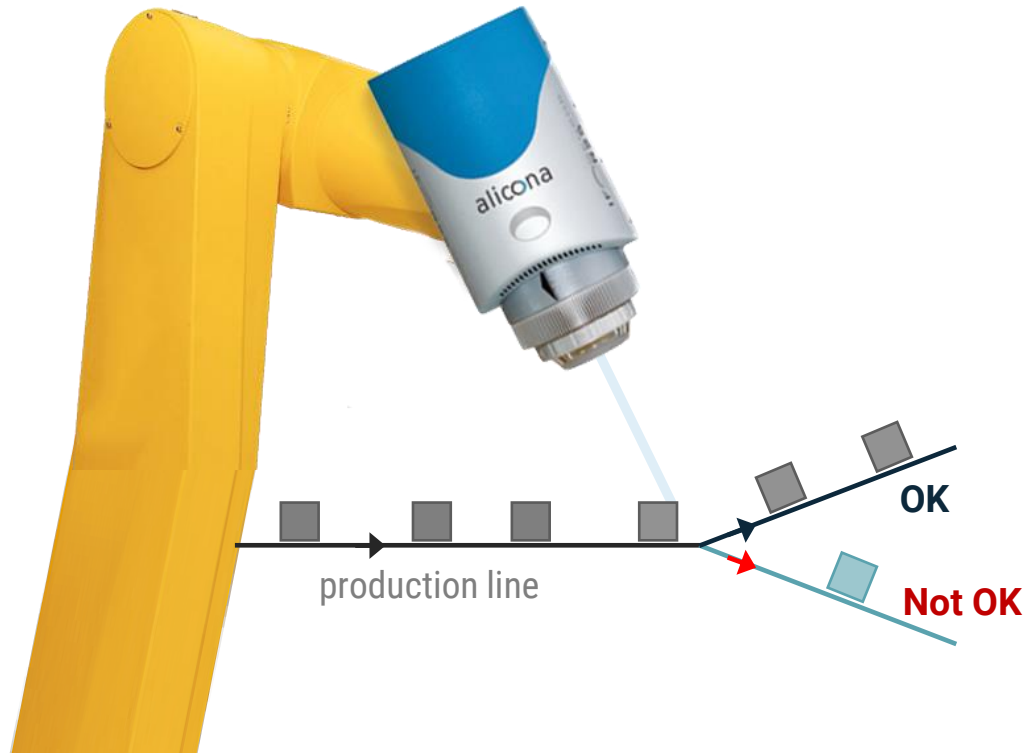
- » Uses the robust technology Focus-Variation
- » Is integrated easily with existing systems
- » Offers automated form and roughness measurement in production
- » Delivers high resolution results with high repeatability and tracability
- » High speed measurement

APPLICATIONS

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Weld Spots Inspection



Measurement of a weld spot

Quality Assurance



Sensor integrated in EDA
(machine tool of Makino)



- » Controlled production
- » Ruling out manufacturing defects
- » 100% control in production

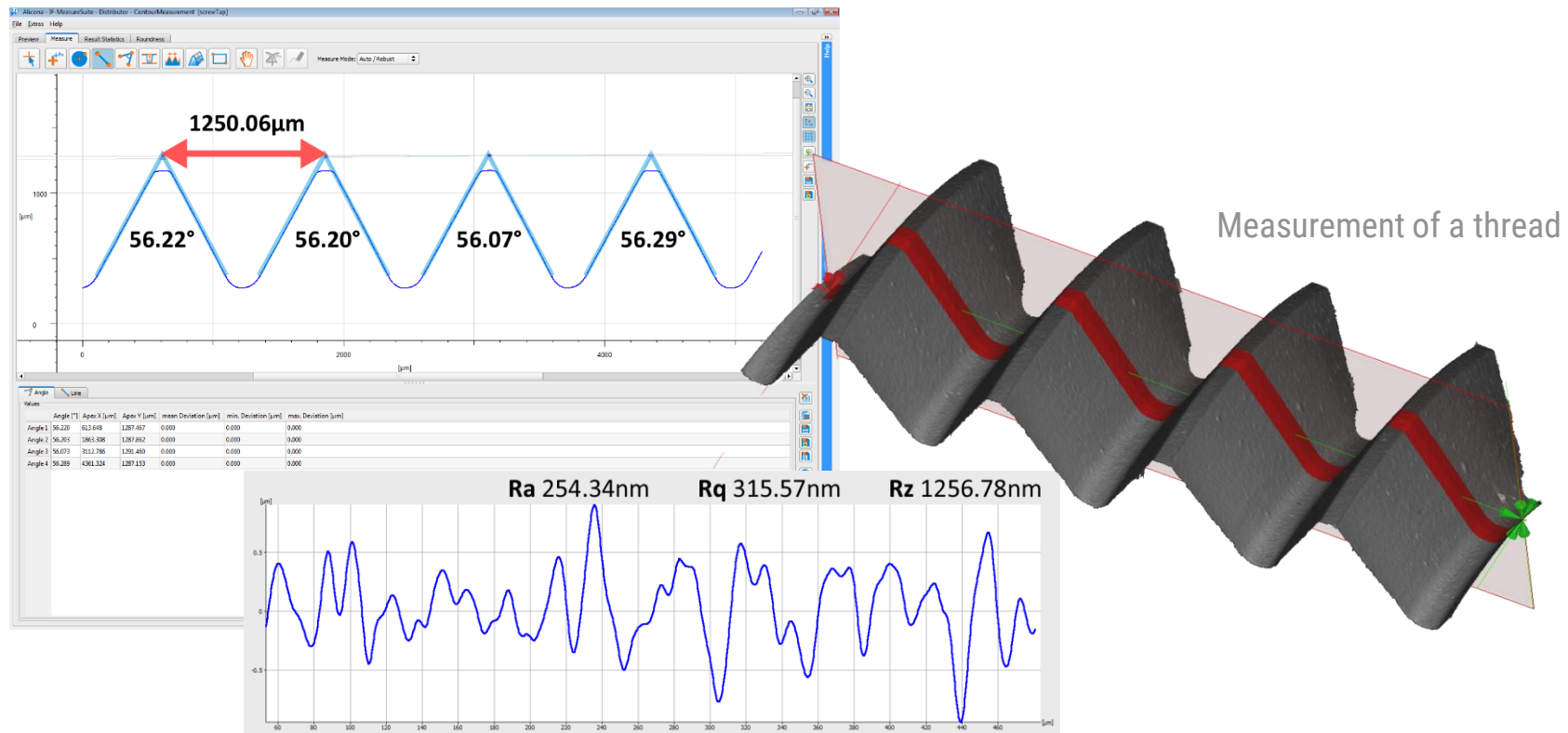
UNIQUE FEATURES

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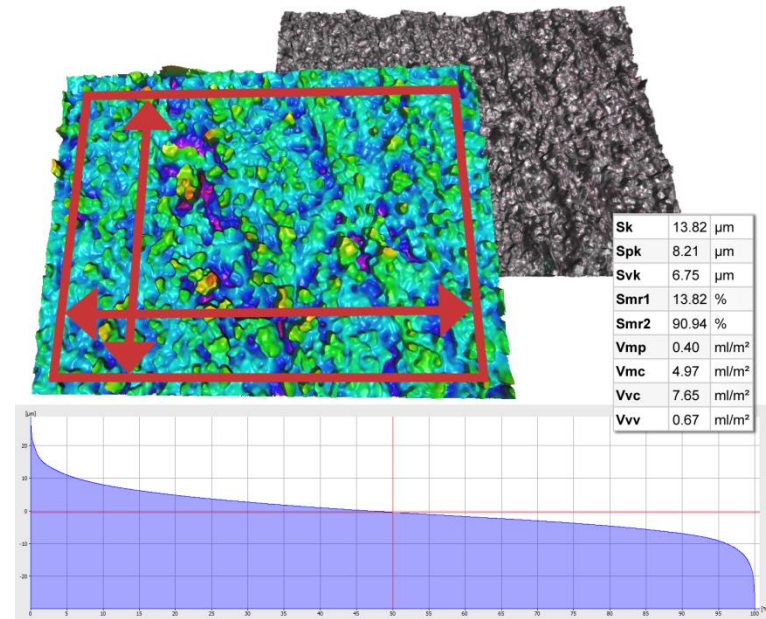
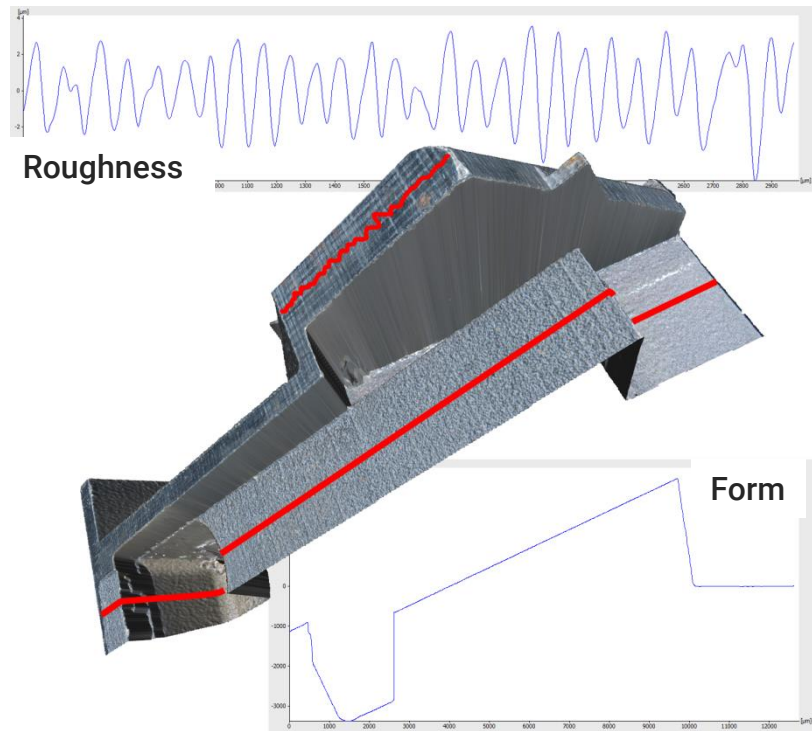
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Form and roughness measurement with only one system



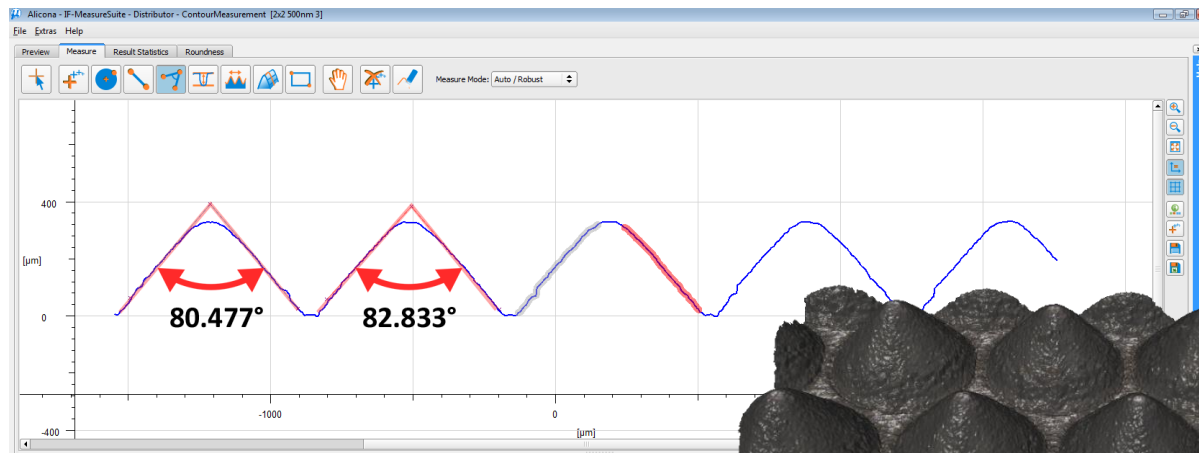
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High resolution, repeatable and traceable surface measurement in production

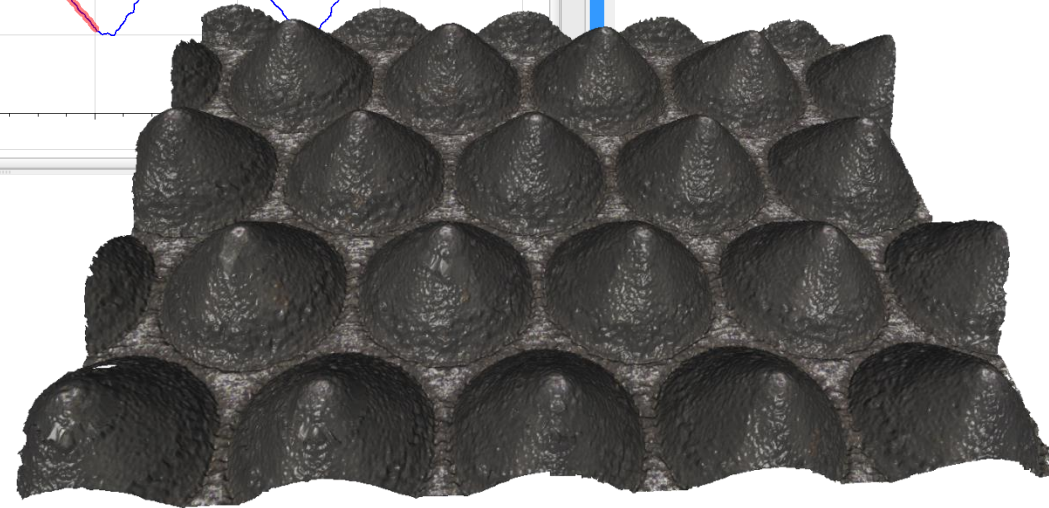


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Measure flanks up to appr. 90°

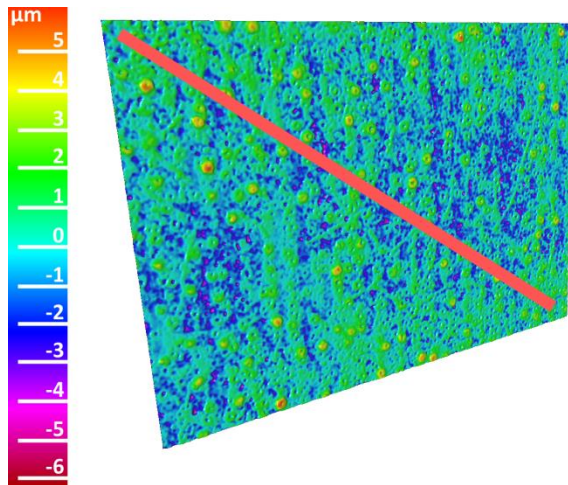


Measurement of a
coining die



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High speed measurement



Example I

Requirement	Areal surface texture measurement
Measurement field	1mm ²
Objective	20x

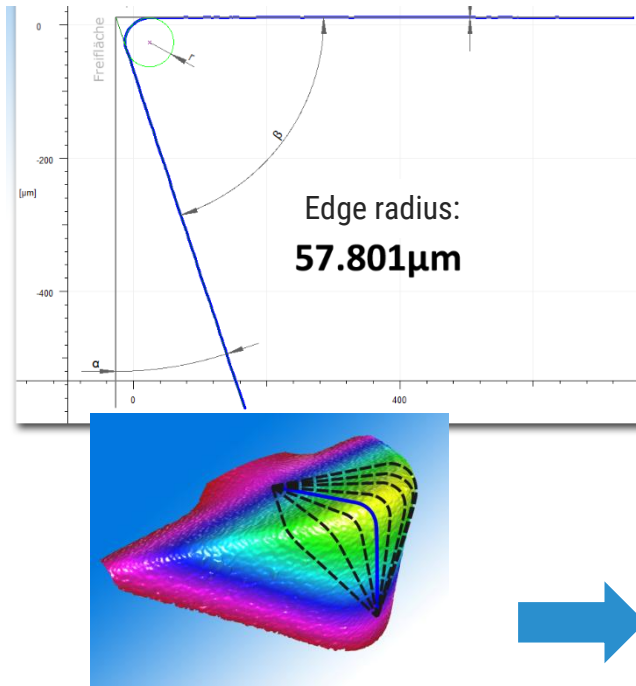
Measurement results within 3 seconds

Measurement time = 2 seconds

Processing time = 1 second

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High speed measurement



Example II

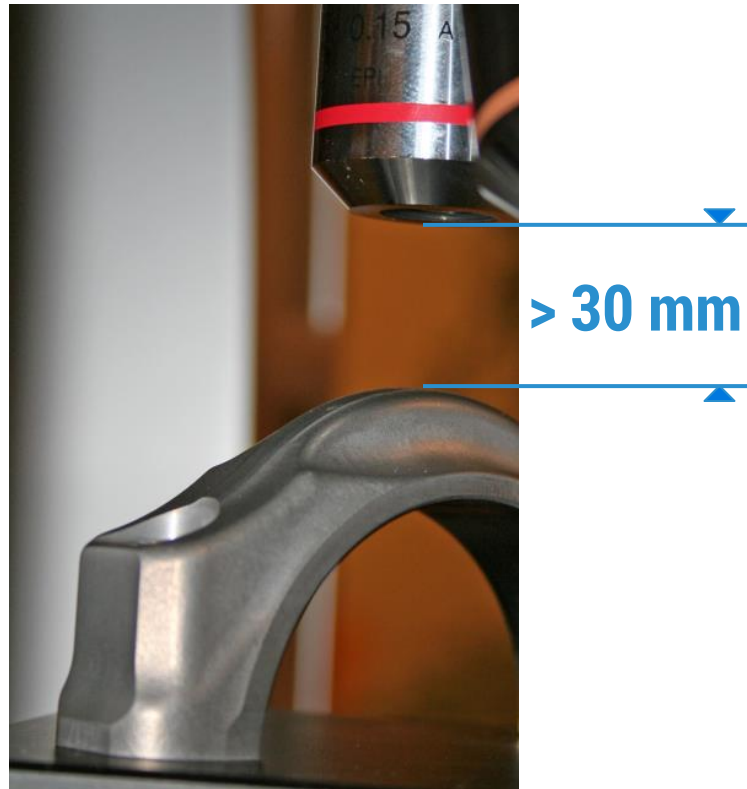
Requirement	Radi measurement
Measurement field	$r = 4\text{mm}$
Objective	5x

Measurement results within 3 seconds

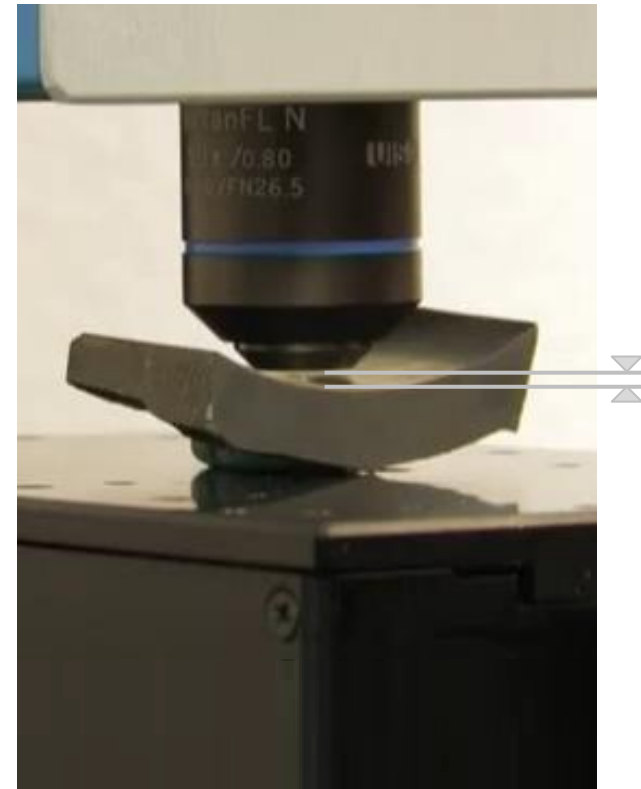
Measurement time = 15 seconds

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For large working distances



Focus-Variation



Conventional methods

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Insensitive to ambient light, temperature fluctuations and vibrations



- » Temperature sensors
- » Vibration sensor

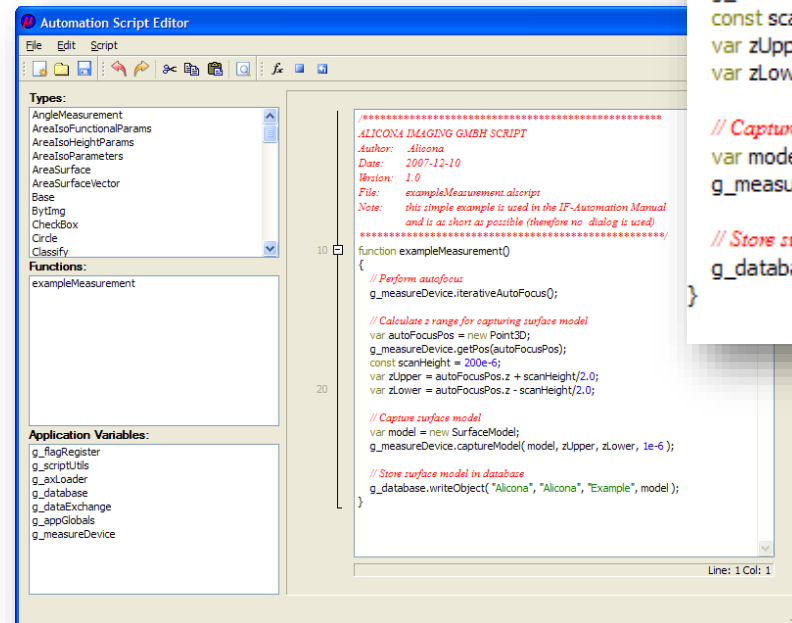
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IF-AutomationModule

Easy integration into production due to a small and light measuring head as well as standardized interfaces



```
// Perform autofocus
g_measureDevice.iterativeAutoFocus();

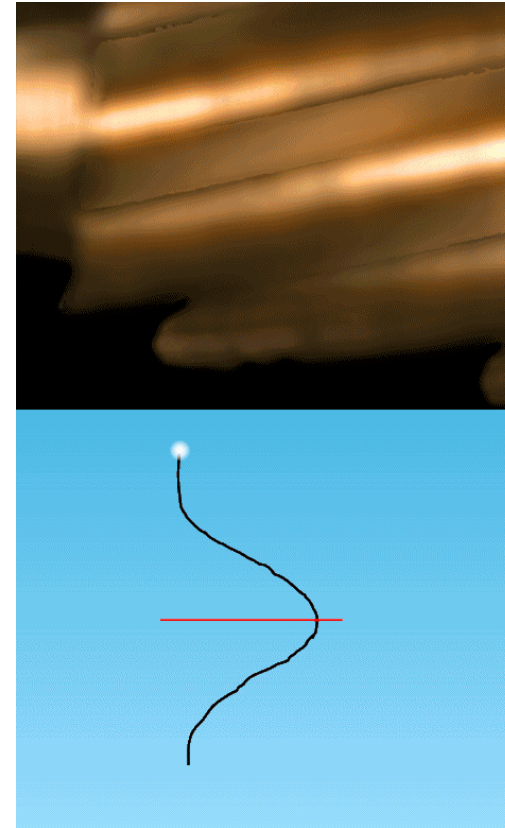
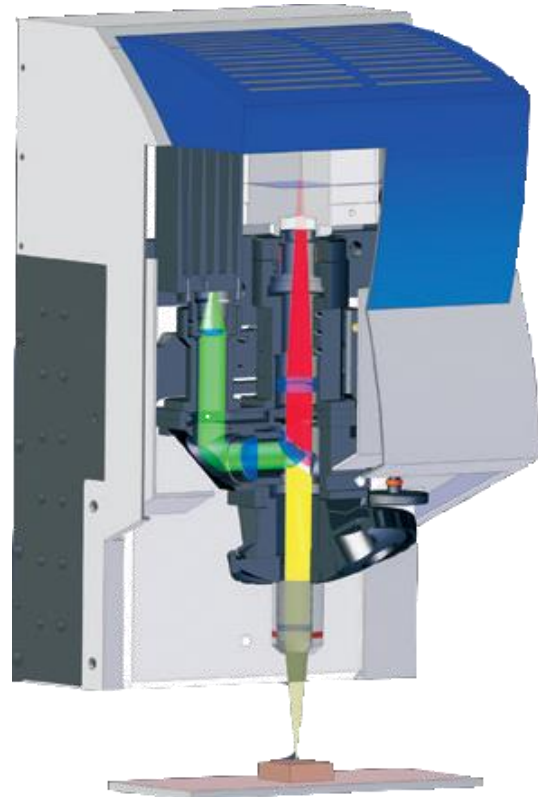
// Calculate z ranges for capturing surface model
var autoFocusPos = new Point3D;
g_measureDevice.getPos(autoFocusPos);
const scanHeight = 200e-6;
var zUpper = autoFocusPos.z + scanHeight/2.0;
var zLower = autoFocusPos.z - scanHeight/2.0;

// Capture surface model
var model = new SurfaceModel;
g_measureDevice.captureModel(model, zUpper, zLower, 1e-6);

// Store surface model in database
g_database.writeObject("Alicona", "Alicona", "Example", model);
```

Script editor

How Focus-Variation Works

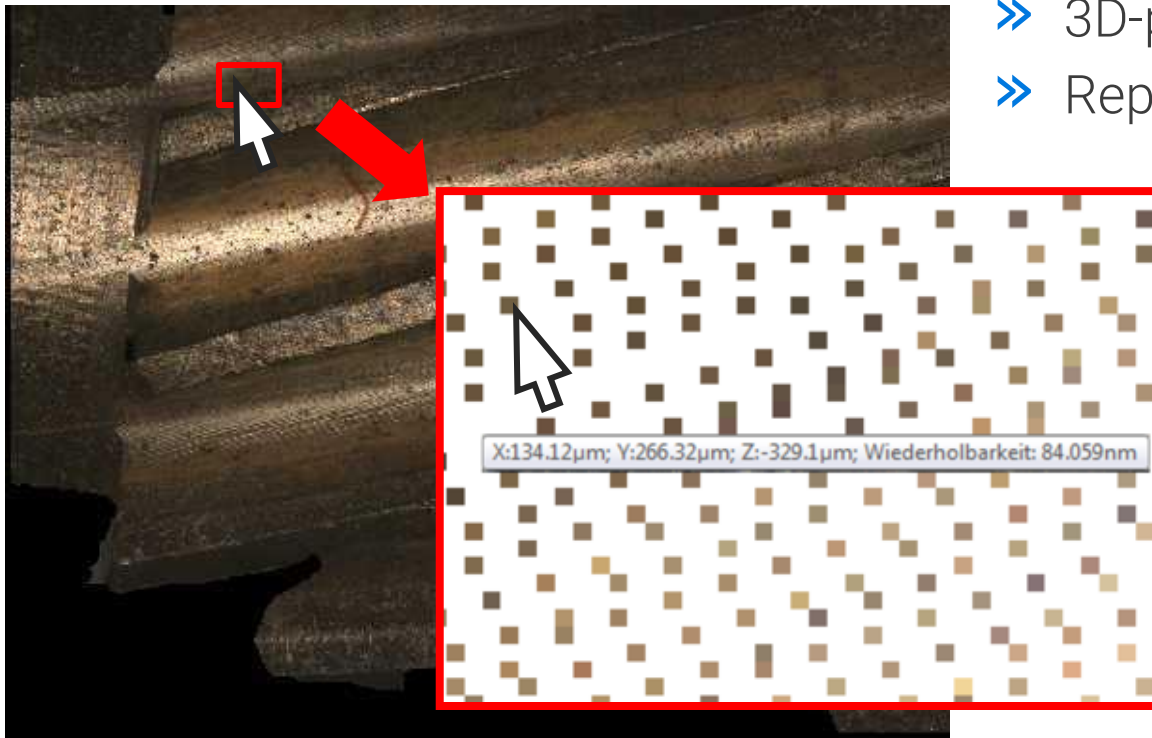


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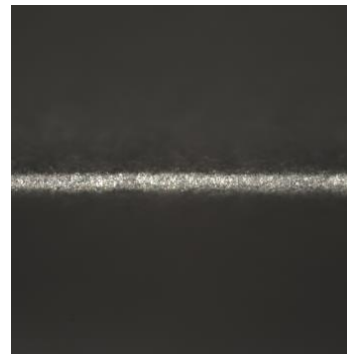
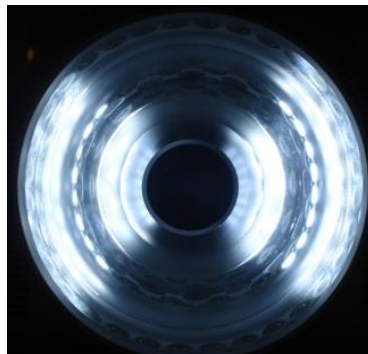
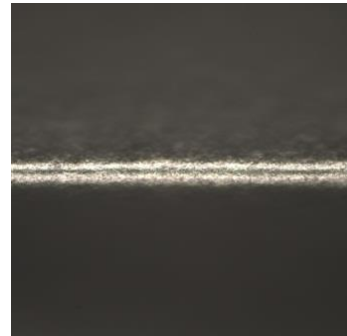
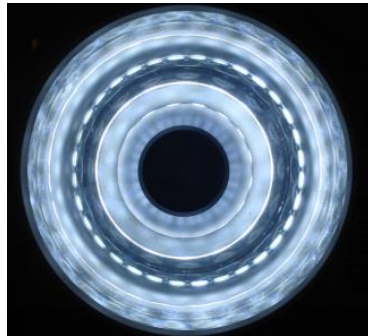
Information of a Dataset

- » True color
- » 3D-position (x, y, z)
- » Repeatability



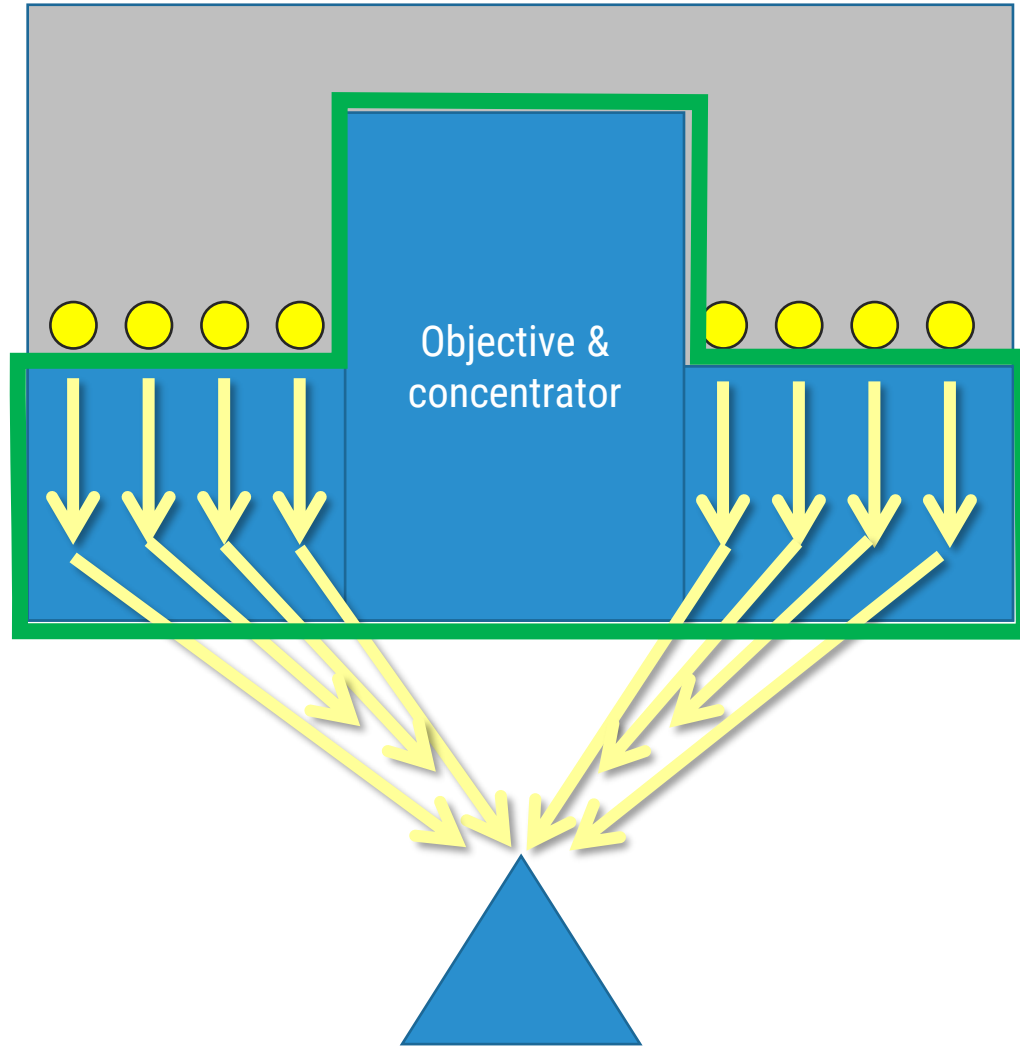
Illumination

- » Motorized polarization
- » Ring light with segments



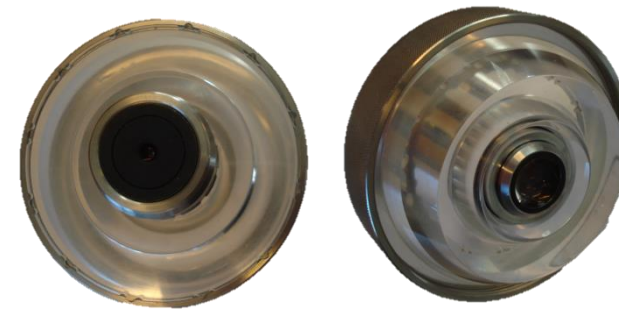
Optimally
illuminated
specimen

Objective with Light Concentrator



Advantages:

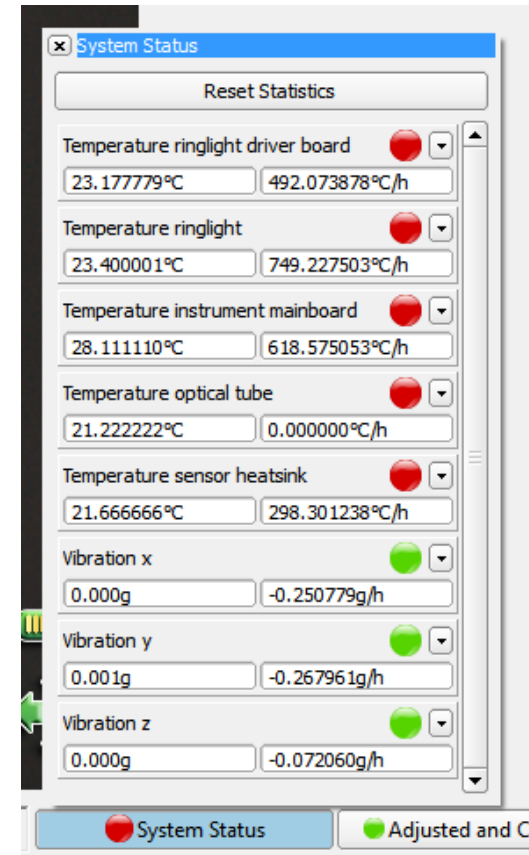
- » A single part
- » Concentrator is optimized for every objective



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Environmental sensors

- » Temperature sensors
 - » Depth Sensor
 - » Optics
 - » Ring light
- » Vibration sensor



With the useful sensors it is possible to evaluate the vibrations and temperatures during a measurement. Therefore valid or invalid conditions are visible for the user.

SYSTEM INTEGRATION

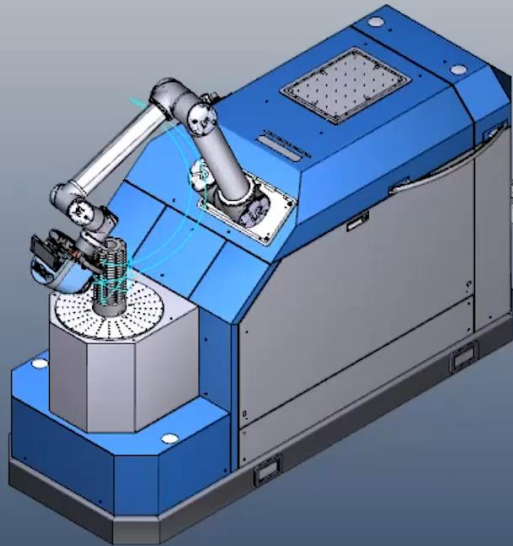
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Smart Manufacturing

Collaborative robots

Simulation of a measurement



Disc Cobot



Tool Cobot

More at  YouTube /aliconaimaging

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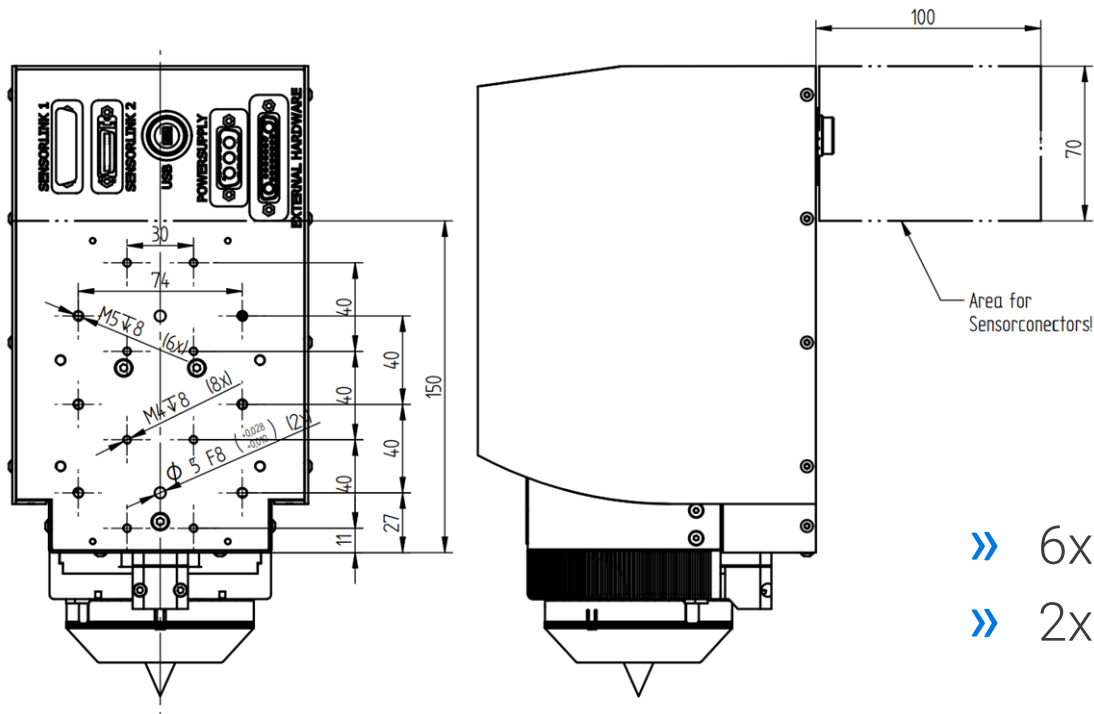
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Electrical Interface

- » Sensorlink1 (IF-ControlServerHP)
- » Sensorlink2 (IF-ControlServerHP)
- » USB (IF-ControlServerHP)
- » Power supply (IF-ControlServerHP)
- » External Hardware (for additional X,Y,R and T-axis)

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Mechanical Interface



- » 6x M5 threads
- » 2x 5F8 dowel hole

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IF-ControlServerHP

- » Compact control unit (WxHxD)
500x450x190mm
- » Simple wiring
- » Integrated power supply for
IF-SensorR25
- » Mountable in 19" housing

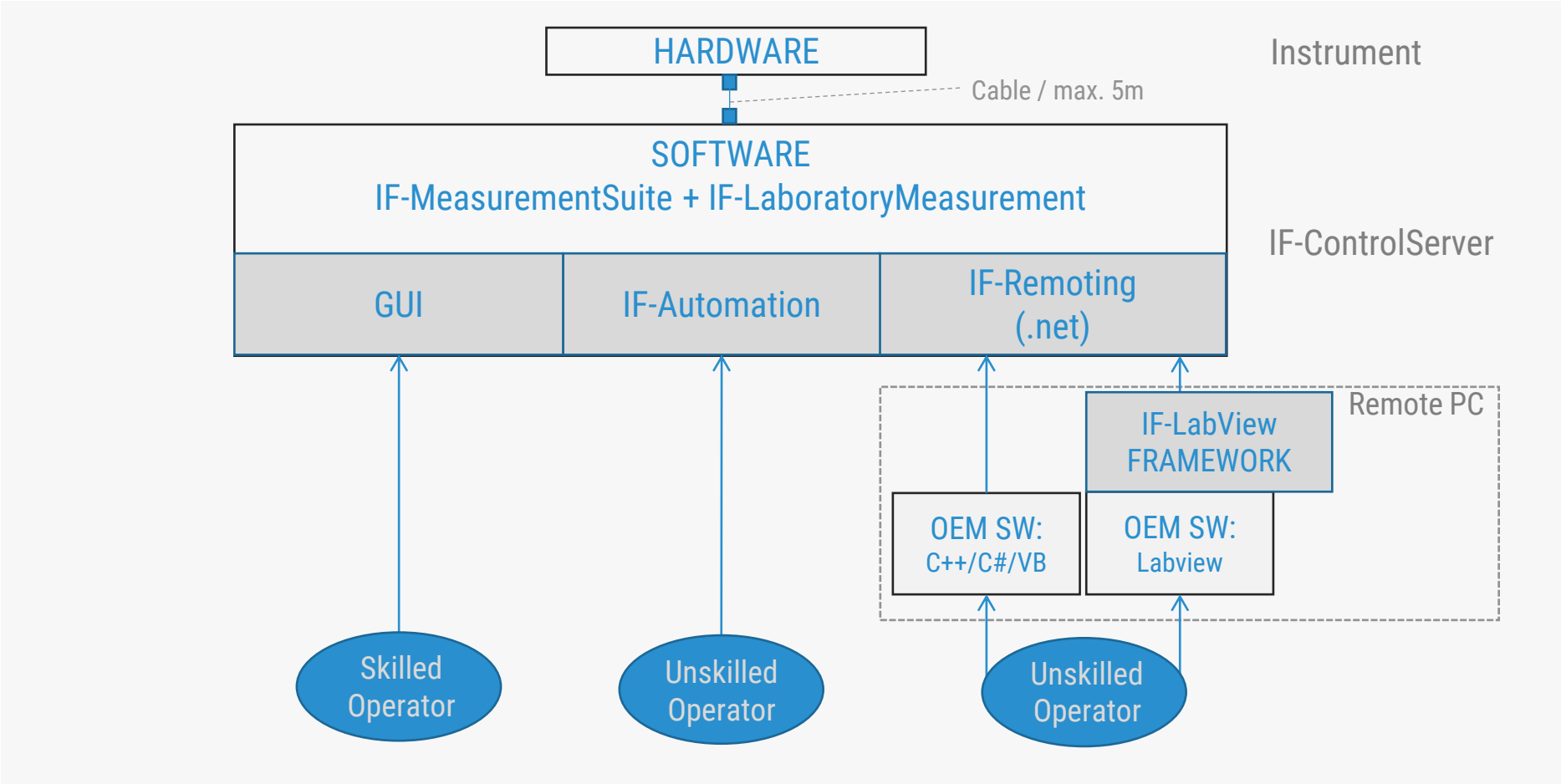
Processor	12 Cores 2x AMD Opteron 4234 3,1GHz
Memory	16 GB
Hard Disk	HD500GB
Graphics Board	Radeon HD7950



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Software Interface

4 x Interface
for flexible use



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Measurement Solutions



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